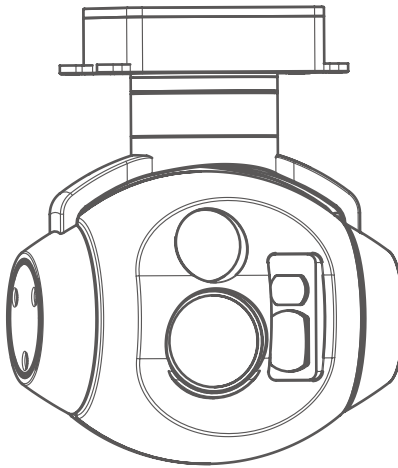
U818M EO + IR Dual-Sensor Laser Rangefinder Object Tracking Gimbal Camera

User Manual



For more details please scan the QR code or visit our website:
www.viewprotech.com

Disclaimer and Warning

Congratulations on purchasing your new Viewpro product. Please read this entire document carefully. Failure to read or follow instructions and warnings in this document may result in damage to your Viewpro product. Disassemble the gimbal camera by user is not permitted, which may cause the camera does not to work normally.

Viewpro accepts no liability for damage, injury or any legal responsibility incurred directly or indirectly from the use of this project. Users of the device are required to follow safe and lawful practices, including but not limited to those outlined in the manual.

Legends

Warning

Important Note

Precautions

1. After using the camera, please store the device in a dry environment to avoid fogging the lens due to excessive ambient humidity. If the lens fogs up, turn on the camera for a while and wait for the fog to dissipate.

2. The camera uses an infrared thermal imaging lens. Do not point it at strong energy sources, such as the sun, laser beams, lava, etc. The temperature of the object observed by the lens must be less than 800°C, otherwise it will burn the camera and cause irreversible damage to it.

3. When cleaning the camera lens, be sure to wipe the lens with a soft and dry cleaning cloth.

4. Do not directly touch or scratch the coating on the surface of the infrared lens with your hands or hard objects, otherwise the coating will be damaged and the image will be blurred.

5. Do not insert or remove the TF card while the power is on; after inserting or removing the TF card, please make sure that the TF rubber plug is tightly covered to prevent the power-on self-test from failing.

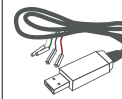
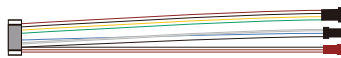
1.Product Introduction

1.1 Introduction

U818M is a 2-axis dual-sensor gimbal camera with a laser rangefinder, which features an 8mm fixed focus lens, 18mm 640*512 IR thermal, and a 1200m Laser rangefinder. U818M supports IR thermal and EO PIP switch, IR color palette switch, photographing and video, target tracking, thermal digital zoom, and so on, also Geo-tagging is workable.

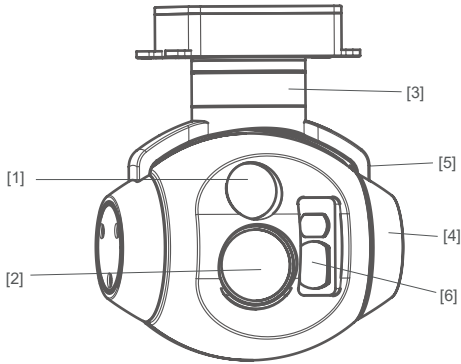
OSD displays the yaw and pitch angle, photo and video status, and tracking frame, and it can also be hidden. When external GPS and time-related protocols are input, the OSD can also display GPS and time; at this time, when taking a photo, the photo attribute has the shooting time and GPS information. Within the distance laser range, the GPS position information at the center of the screen can be displayed. It can achieve stabilization in both yawl and pitch directions. U818M adopts the integrated design of shock absorption and gimbal, which can greatly reduce mechanical vibration. It is widely used in drone applications such as public security, electric power, fire protection, and zoom aerial photography.

1.2 In the Box

Gimbal camera*1pc		USB to TTL cable *1pc	
Aluminum Cylinder *4		M3 Screw *8	
Power cable*1pc			
TTL connect cable *1pc			
Ethernet cable *1pc			
Multi-function cable*1pc			

2.Installation Instruction

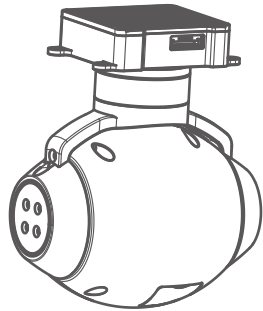
2.1 Overview

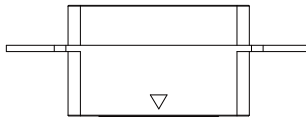


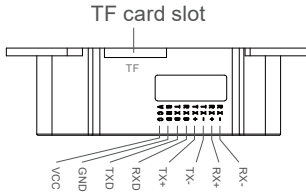
[1] FHD zoom camera
[2] Infrared thermal camera
[3] Yaw axis motor
[4] Pitch axis motor
[5] TF card slot
[6] laser rangefinder

- Please ensure that there isn't any obstacle while the motor rotating.
- Please remove the obstacle immediately if gimbal camera is blocked during rotation.
- Don't put the infrared thermal camera towards the sun in case any burn to the camera.

2.2 Control box silk screen

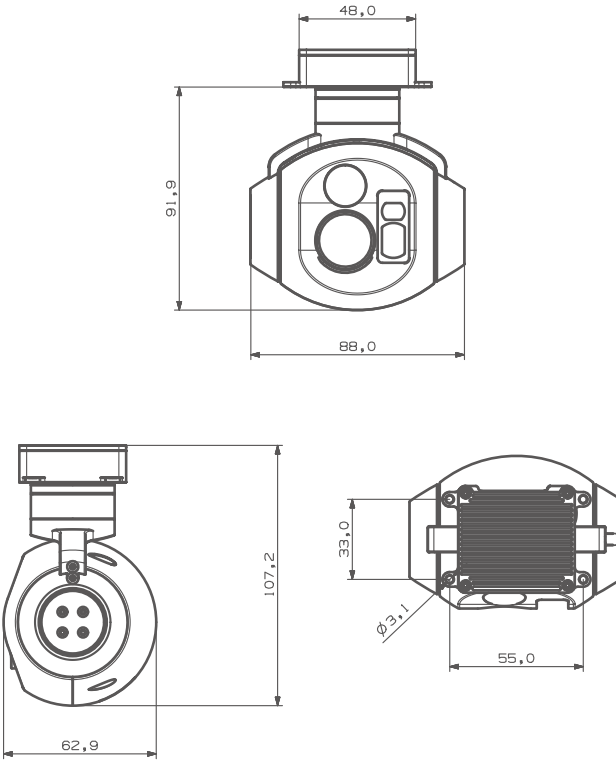






2.2 Device Dimensions (Standard Version)

Unit: mm

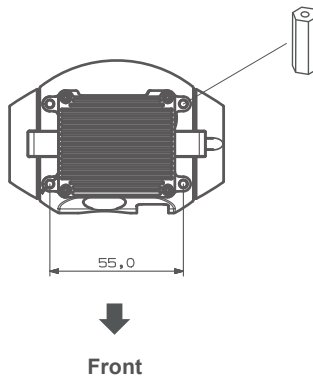


2.3 Mounting Part Installation

(1) Find out the arrow on the gimbal which indicating the yaw heading of the payload (i.e. the lens direction when the camera power on), and synchronize with the direction specified by the UAV.

(2) Fix one end of the copper cylinder on the screw hole of lower damping board, and use M3 screw to fasten it.

(3) According to the provided screw hole dimension you can make suitable mounting holes on the UAV mounting board, and fixes the other end of the copper cylinder on the mounting board of the UAV (Viewport version is the same).



2.4 TF Card Installation

TF (Micro SD card):

TF (Micro SD card): Install the TF card to the card slot (Re. 3.1 Overview). Support max 512GB. Request Class 10 (10m/s) transmission speed or higher and FAT32.

- Make sure device is power off when inserting the TF card, hot plugging is not supported.

2.5 Image Output Interface

Ethernet: Ethernet/IP output interface, support RTSP video streaming. Default: RTSP output, IP address: rtsp://192.168.2.119:554, output resolution: 720P, frame rate: 30fps, bit rate: 2M.

- When using Viewlink for network connection, the network of external device (computer) should be the IP address: 192.168.2.2 (choose the last byte among 2~254, can not be 119 same as the gimbal), subnet mask: 255.255.255.0, Default gateway: 192.168.2.1, and all firewalls of the computer must be closed. Then enter the IP address of the gimbal camera, Open Video, the video stream can be outputted.

3. Signal Control

3.1 Serial Port / TTL Control

TTL communication requirements: TTL signal is 3.3V, baud rate: 115200, data bit 8, stop bit 1, no parity, HEX send and receive.

Connection Diagram (PC - USB to TTL Cable- Gimbal Camera as example):

Gimbal Camera		Cable
TX	⟷	RX (White)
RX	⟷	TX (Green)
GND	⟷	GND (Black)

Diagram of USB to TTL Cable:

Connect the camera to the upper computer by USB to TTL cable (Adopt connection method of TX to RX, RX to TX, GND to GND at Dupont ends of the provided USB to TTL cable, connect to the specified TTL of the gimbal, and the USB end of the cable connect to computer).

Install Viewlink control software to test the functions directly. Users may choose to develop their own software, please contact technical support for TTL control protocol file.

ViewLink is a user interface developed by Viewpro for Viewpro gimbal cameras, you can download it from Viewpro website (www.viewprotech.com) or ask distributors for installation package.

- Connect serial port of gimbal to pins, DO NOT connect with power supply.

- The default baud rate of serial port is 115200, which can be changed according to the docking equipment.

3.2 S.BUS

Send commands through the serial port TTL/network port TCP to force the serial port to be used as the S.bus interface.

S.Bus control mode: default S.Bus signal channel 7-13 to control gimbal camera functions (the function of channel is consistent with the corresponding channel in PWM function description)

Channel 7: Yaw Control
Channel 8: Pitch Control
Channel 9: Mode Control
Channel 10: Zoom Control
Channel 11: Focus Control
Channel 12: Pic/Rec Control
Channel 13: Multi Backup

S.bus remote control operating instructions:

1) Pitch (S.BUS Pitch channel in to control Pitch. Joystick, rotary knob or 3-gear switch on remote control are optional. 3-gear switch as example.)

Position 1

Low Gear
Pitch Up

Position 2

Middle Gear
Pitch Stop

Position 3

High Gear
Pitch Down

2) Yaw (S.BUS Yaw channel in to control Yaw. Joystick, rotary knob or 3-gear switch on remote control are optional. 3-gear switch as example.)

Position 1

Low Gear
Yaw Left

Position 2

Middle Gear
Yaw Stop

Position 3

High Gear
Yaw Right

3) Mode (SBUS Mode channel in to adjust speed control/one key to Home position etc functions. Rotary knob or 3-gear switch on remote control are optional. 3-gear switch as example.)

Position 1

Low Gear

Position 2

Middle Gear

Position 3

High Gear

Position 1: Low speed mode, control pitch / yaw with this mode at lowest speed;
Position 2: Middle speed mode, control pitch / yaw with this mode at middle speed;
Position 3: High speed mode, control pitch / yaw with this mode at highest speed;
(If it is controlled by rotary knob, the speed will change according to switch position)

4) Function of continuous switching:

4-1) Operate 1 time continuously and quickly, from position 2 - 3, to Home position.

4-2) Operate 2 times continuously and quickly, from position 2 - 3 - 2 - 3, the camera lens looks vertically down.

4-3) Operate 3 times continuously and quickly, from position 2 - 3 - 2 - 3 - 2 - 3, to disable Follow Yaw Mode (gimbal yaw not follows by frame)

4-4) Operate 4 times continuously and quickly, from position 2 - 3 - 2 - 3 - 2 - 3 - 2 - 3, to enable Follow Yaw Mode (gimbal yaw follows by frame)

5) Zoom (PWM Zoom channel in to control Zoom. Joystick, rotary knob or 3-gear switch on remote control are optional. 3-gear switch as example.)

Position 1

Low Gear
Zoom Out

Position 2

Middle Gear
Stop Zoom

Position 3

High Gear
Zoom In

6) Focus (PWM Focus channel is to control PIP, IR color palette switch, 3-gear switch as example.)

Position 1

Low Gear
No control

Position 2

Middle Gear
No control

Position 3

High Gear
IR color palette switch

Switch from Position 2 to 3: IR color switching: white hot, black hot, pseudo color.

7) Pic/Rec (PWM Pic/Rec channel in to control take picture and record. Joystick, rotary knob or 3-gear switch on remote control are optional. 3-gear switch as example.)

Position 1

Low Gear

Position 2

Middle Gear

Position 3

High Gear

Switch from Position 2 to 1: Take a picture

- OSD display 'SNAP' a second.

Switch from Position 2 to 3: Start record / repeat operation to stop record

- Start record, the OSD display rec hh:mm:ss.

Stop record, the OSD display SDcard xx min left.

8) Multi: IR digital zoom / tracking control

Position 1

Low Gear

Position 2

Middle Gear

Position 3

High Gear

Switch from Position 2 to 1:

- IR digital zoom, 1x~4x

Switch from Position 2 to 3:

- Exit the tracking, display the cross cursor. Adjust the cross cursor to lock target object and start tracking

Switch from Position 3 to 2:

- Cancel tracking

- User can set the channels by setting serial command according to the actual requirement. The S.Bus channel position can be arranged in any sequence within channel 1-15 to connect with the flight controller or remote control.
- TTL control and S.bus control cannot coexist at the same time for standard version. The defualt control is TTL if no requirement. The user can set to S.bus control if needed (please contact with our technical support for the setting instruction.)

3.4 TCP control

For Viewpro gimbal cameras with Ethernet output, the default IP address is: 192.168.2.119, control port: 2000. You can send the corresponding protocol to realize TCP control after connecting.

The TCP control protocol is [Frame header: EB + command ID: 90 + data body (serial port protocol) + Checksum (CS = body checksum, checksum is calculated as a sum of all bytes of data body modulo 256)]. Or directly use UI Viewlink to control after TCP connection.

4.Specifications

Hardware Parameters	
Working voltage	16V
Input voltage	4S ~ 6S (14.8V~25.2V)
Dynamic current	540~900mA @ 16V
Power consumption	Average 8W, Max 14.4W
Working environment temp.	-20℃ ~ +40℃
Output	IP (RTSP/UDP 720p/1080p 25fps/30fps H264/H265)
Local-storage	SD card (Up to 512G,class 10, FAT32 format)
Picture storage format in TF card	JPG(1920*1080)
Video storage format in TF card	MP4(1080P 30fps)
Control method	TTL or S.BUS (choose one of them, and TTL by default), and TCP/UDP
Gimbal Spec	
Mechanical Range	Pitch/Tilt: -55°～125°, Yaw/Pan: ±360°*N
Controllable Range	Pitch/Tilt: -45°～120°, Yaw/Pan: ±360°*N
Vibration angle	Pitch/Yaw: ±0.02°
One-key to center	√

EO Camera Spec	
Imager Sensor	CMOS Sensor
Resolution	1920*1080
Focus Length	8mm
Angle of View	38.3°*22.1°
Digital zoom	1x ~ 8x
Detective Distance (Car: 4.2x1.8m)	2000m
Recognize Distance (Car: 4.2x1.8m)	1000m
Recognize Distance (Man: 1.8x0.5m)	400m

IR Thermal Imager Spec	
Focus Length	18mm
Horizontal FOV	24°
Vertical FOV	18.1°
Working mode	Uncooled VOx long wave (8μm~14μm) thermal imager
Detector pixel	640*512
Pixel size	12μm
Focusing method	Athermal prime lens
NETD	≤50mK@F1.0 @25℃

Color palette	White hot, black hote, pseudo color
Digital zoom	1x ~ 8x
Detective Distance (Car: 4.2x1.8m)	1000m
Recognize Distance (Car: 4.2x1.8m)	500m
Recognize Distance (Man: 1.8x0.5m)	250m
EO / IR Camera Object Tracking	
Update rate of deviation pixel	60Hz
Minimum object contrast	5%
Minimum object size	16*16 pixel
Maximum object size	128*128 pixel
Tracking speed	±48 pixel/frame
Object memory time	100 frames
IR Laser Rangefinder	
Range	5~1200 meters
Resolution	1m
Light Beam	905nm pulse laser
Divergent Angle	~6 mrad
Laser pulse frequency	1~4Hz
Location Resolving	Latitude and longitude of target

Ranefinder	Measure the distance between the object at the center of screen and the laser rangefinder
Features	
OSD	Display the gimbal's yaw and pitch angle, magnification, card recording duration, aircraft GPS and altitude, date and time
Geotagging	Display time and GPS coordinate in picture exif
Card reading online	SMB read pictures or videos / HTTP read pictures or videos
KLV (UDP) (optional)	Card recording or Viewlink video playback
ArduPilot / PX4	Support(Mavlink protocol) Optional: Support Ardupilot Follow me feature
Video stitching	EO+IR /IR+EO /EO /IR
Dual video stream output	Not support(EO and IR two stream output)
Packing Information	
N.W.	319g
Product meas.	88.2*62.9*107.2mm

5.FAQ

1.Does U818M support taking photos during recording?
A: Yes

How are the photos and videos of the U818M stored?
A: The photo saved in the TF card is JPG 1920*1080, and the video is 1080P30fps in MP4 format;

3. How to modify the encoding parameters of U818M?
A: Through the Viewlink upper computer software, enter the pod mesh door (default IP: 192.168.2.119, Port: 2000), after establishing a TCP connection, go to “Encoding Settings” to make modifications.

This user manual is subject to update without notice. For details, please visit http://www.viewprotech.com/index.php to get the latest product information.
Technical support : support@viewprotech.com